Foundations of Machine Learning Learning with Infinite Hypothesis Sets

Motivation

- With an infinite hypothesis set H, the error bounds of the previous lecture are not informative.
- Is efficient learning from a finite sample possible when H is infinite?
- Our example of axis-aligned rectangles shows that it is possible.
- Can we reduce the infinite case to a finite set? Project over finite samples?
- Are there useful measures of complexity for infinite hypothesis sets?

This lecture

- Rademacher complexity
- Growth Function
- VC dimension
- Lower bound

Empirical Rademacher Complexity

Definition:

- G family of functions mapping from set Z to [a, b].
- sample $S = (z_1, ..., z_m)$.
- σ_i s (Rademacher variables): independent uniform random variables taking values in $\{-1, +1\}$.

$$\widehat{\mathfrak{R}}_{S}(G) = \mathop{\mathrm{E}}_{\sigma} \left[\sup_{g \in G} \frac{1}{m} \begin{bmatrix} \sigma_{1} \\ \vdots \\ \sigma_{m} \end{bmatrix} \cdot \begin{bmatrix} g(z_{1}) \\ \vdots \\ g(z_{m}) \end{bmatrix} \right] = \mathop{\mathrm{E}}_{\sigma} \left[\sup_{g \in G} \frac{1}{m} \sum_{i=1}^{m} \sigma_{i}g(z_{i}) \right].$$
correlation with random noise

Rademacher Complexity

- Definitions: let G be a family of functions mapping from Z to [a, b].
 - Empirical Rademacher complexity of G:

$$\widehat{\mathfrak{R}}_{S}(G) = \mathop{\mathrm{E}}_{\sigma} \left[\sup_{g \in G} \frac{1}{m} \sum_{i=1}^{m} \sigma_{i} g(z_{i}) \right],$$

where σ_i s are independent uniform random variables taking values in $\{-1, +1\}$ and $S = (z_1, \dots, z_m)$.

• Rademacher complexity of G:

$$\mathfrak{R}_m(G) = \mathop{\mathrm{E}}_{S \sim D^m} [\widehat{\mathfrak{R}}_S(G)].$$

Rademacher Complexity Bound

(Koltchinskii and Panchenko, 2002)

Theorem: Let G be a family of functions mapping from Z to [0, 1]. Then, for any $\delta > 0$, with probability at least $1 - \delta$, the following holds for all $g \in G$:

$$\mathbf{E}[g(z)] \leq \frac{1}{m} \sum_{i=1}^{m} g(z_i) + 2\mathfrak{R}_m(G) + \sqrt{\frac{\log \frac{1}{\delta}}{2m}}.$$
$$\mathbf{E}[g(z)] \leq \frac{1}{m} \sum_{i=1}^{m} g(z_i) + 2\widehat{\mathfrak{R}}_S(G) + 3\sqrt{\frac{\log \frac{2}{\delta}}{2m}}.$$

Proof: Apply McDiarmid's inequality to

$$\Phi(S) = \sup_{g \in G} \mathcal{E}[g] - \widehat{\mathcal{E}}_S[g].$$

• Changing one point of S changes $\Phi(S)$ by at most $\frac{1}{m}$.

$$\Phi(S') - \Phi(S) = \sup_{g \in G} \{ \mathbf{E}[g] - \widehat{\mathbf{E}}_{S'}[g] \} - \sup_{g \in G} \{ \mathbf{E}[g] - \widehat{\mathbf{E}}_{S}[g] \}$$

$$\leq \sup_{g \in G} \{ \{ \mathbf{E}[g] - \widehat{\mathbf{E}}_{S'}[g] \} - \{ \mathbf{E}[g] - \widehat{\mathbf{E}}_{S}[g] \} \}$$

$$= \sup_{g \in G} \{ \widehat{\mathbf{E}}_{S}[g] - \widehat{\mathbf{E}}_{S'}[g] \} = \sup_{g \in G} \frac{1}{m} (g(z_m) - g(z'_m)) \le \frac{1}{m}.$$

• Thus, by McDiarmid's inequality, with probability at least $1 - \frac{\delta}{2}$

$$\Phi(S) \le \mathop{\mathrm{E}}_{S}[\Phi(S)] + \sqrt{\frac{\log \frac{2}{\delta}}{2m}}.$$

• We are left with bounding the expectation.

• Series of observations:

$$\begin{split} \mathbf{E}_{S}[\Phi(S)] &= \mathbf{E}_{S}\left[\sup_{g \in G} \mathbf{E}[g] - \widehat{\mathbf{E}}_{S}(g)\right] \\ &= \mathbf{E}_{S}\left[\sup_{g \in G} \mathbf{E}_{S}[\widehat{\mathbf{E}}_{S'}(g) - \widehat{\mathbf{E}}_{S}(g)]\right] \\ (\text{sub-add. of sup}) &\leq \mathbf{E}_{S,S'}\left[\sup_{g \in G} \widehat{\mathbf{E}}_{S'}(g) - \widehat{\mathbf{E}}_{S}(g)\right] \\ &= \mathbf{E}_{S,S'}\left[\sup_{g \in G} \frac{1}{m} \sum_{i=1}^{m} (g(z'_{i}) - g(z_{i}))\right] \\ (\text{swap } z_{i} \text{ and } z'_{i}) &= \mathbf{E}_{\sigma,S,S'}\left[\sup_{g \in G} \frac{1}{m} \sum_{i=1}^{m} \sigma_{i}(g(z'_{i}) - g(z_{i}))\right] \\ (\text{sub-additiv. of sup}) &\leq \mathbf{E}_{\sigma,S'}\left[\sup_{g \in G} \frac{1}{m} \sum_{i=1}^{m} \sigma_{i}g(z'_{i})\right] + \mathbf{E}_{\sigma,S}\left[\sup_{g \in G} \frac{1}{m} \sum_{i=1}^{m} - \sigma_{i}g(z_{i})\right] \\ &= 2 \mathbf{E}_{\sigma,S}\left[\sup_{g \in G} \frac{1}{m} \sum_{i=1}^{m} \sigma_{i}g(z_{i})\right] = 2\mathfrak{R}_{m}(G). \end{split}$$

• Now, changing one point of S makes $\widehat{\Re}_S(G)$ vary by at most $\frac{1}{m}$. Thus, again by McDiarmid's inequality, with probability at least $1 - \frac{\delta}{2}$,

$$\mathfrak{R}_m(G) \le \widehat{\mathfrak{R}}_{\mathcal{S}}(G) + \sqrt{\frac{\log \frac{2}{\delta}}{2m}}.$$

• Thus, by the union bound, with probability at least $1-\delta$,

$$\Phi(S) \le 2\widehat{\mathfrak{R}}_S(G) + 3\sqrt{\frac{\log \frac{2}{\delta}}{2m}}.$$

Loss Functions - Hypothesis Set

Proposition: Let H be a family of functions taking values in $\{-1, +1\}$, G the family of zero-one loss functions of H: $G = \{(x, y) \mapsto 1_{h(x) \neq y} : h \in H\}$. Then,

$$\mathfrak{R}_m(G) = \frac{1}{2}\mathfrak{R}_m(H).$$

Proof:
$$\Re_m(G) = \mathop{\mathrm{E}}_{S,\sigma} \left[\sup_{h \in H} \frac{1}{m} \sum_{i=1}^m \sigma_i \mathbf{1}_{h(x_i) \neq y_i} \right]$$

$$= \mathop{\mathrm{E}}_{S,\sigma} \left[\sup_{h \in H} \frac{1}{m} \sum_{i=1}^m \sigma_i \frac{1}{2} (1 - y_i h(x_i)) \right]$$

$$= \frac{1}{2} \mathop{\mathrm{E}}_{S,\sigma} \left[\sup_{h \in H} \frac{1}{m} \sum_{i=1}^m -\sigma_i y_i h(x_i) \right]$$

$$= \frac{1}{2} \mathop{\mathrm{E}}_{S,\sigma} \left[\sup_{h \in H} \frac{1}{m} \sum_{i=1}^m \sigma_i h(x_i) \right].$$

Generalization Bounds - Rademacher

Corollary: Let H be a family of functions taking values in $\{-1, +1\}$. Then, for any $\delta > 0$, with probability at least $1 - \delta$, for any $h \in H$,

$$R(h) \leq \widehat{R}(h) + \Re_m(H) + \sqrt{\frac{\log \frac{1}{\delta}}{2m}}.$$
$$R(h) \leq \widehat{R}(h) + \widehat{\Re}_S(H) + 3\sqrt{\frac{\log \frac{2}{\delta}}{2m}}.$$

Remarks

- First bound distribution-dependent, second datadependent bound, which makes them attractive.
- But, how do we compute the empirical Rademacher complexity?
- Computing $E_{\sigma}[\sup_{h \in H} \frac{1}{m} \sum_{i=1}^{m} \sigma_i h(x_i)]$ requires solving ERM problems, typically computationally hard.
- Relation with combinatorial measures easier to compute?

This lecture

- Rademacher complexity
- Growth Function
- VC dimension
- Lower bound

Growth Function

Definition: the growth function $\Pi_H : \mathbb{N} \to \mathbb{N}$ for a hypothesis set *H* is defined by

 $\forall m \in \mathbb{N}, \ \Pi_H(m) = \max_{\{x_1, \dots, x_m\} \subseteq X} \left| \left\{ (h(x_1), \dots, h(x_m)) : h \in H \right\} \right|.$

Thus, $\Pi_H(m)$ is the maximum number of ways m points can be classified using H.

Massart's Lemma

(Massart, 2000)

Theorem: Let $A \subseteq \mathbb{R}^m$ be a finite set, with $R = \max_{x \in A} ||x||_2$, then, the following holds:

$$\begin{split} \mathbf{E}_{\sigma} \left[\frac{1}{m} \sup_{x \in A} \sum_{i=1}^{m} \sigma_{i} x_{i} \right] &\leq \frac{R\sqrt{2\log|A|}}{m}. \\ \mathbf{Proof:} \exp\left(t \mathop{\mathbb{E}}_{\sigma} \left[\sup_{x \in A} \sum_{i=1}^{m} \sigma_{i} x_{i} \right] \right) &\leq \mathop{\mathbb{E}}_{\sigma} \left(\exp\left[t \sup_{x \in A} \sum_{i=1}^{m} \sigma_{i} x_{i} \right] \right) \quad \text{(Jensen's ineq.)} \\ &= \mathop{\mathbb{E}}_{\sigma} \left(\sup_{x \in A} \exp\left[t \sum_{i=1}^{m} \sigma_{i} x_{i} \right] \right) \\ &\leq \sum_{x \in A} \mathop{\mathbb{E}}_{\sigma} \left(\exp\left[t \sum_{i=1}^{m} \sigma_{i} x_{i} \right] \right) = \sum_{x \in A} \mathop{\mathbb{E}}_{\sigma} \left(\exp\left[t \sigma_{i} x_{i} \right] \right) \\ &\text{(Hoeffding's ineq.)} &\leq \sum_{x \in A} \left(\exp\left[\frac{\sum_{i=1}^{m} t^{2} (2|x_{i}|)^{2}}{8} \right] \right) \leq |A| e^{\frac{t^{2} R^{2}}{2}}. \end{split}$$

• Taking the log yields:

$$\operatorname{E}_{\sigma}\left[\sup_{x\in A}\sum_{i=1}^{m}\sigma_{i}x_{i}\right] \leq \frac{\log|A|}{t} + \frac{tR^{2}}{2}.$$

• Minimizing the bound by choosing $t = \frac{\sqrt{2 \log |A|}}{R}$ gives

$$\operatorname{E}_{\sigma}\left[\sup_{x\in A}\sum_{i=1}^{m}\sigma_{i}x_{i}\right] \leq R\sqrt{2\log|A|}.$$

Growth Function Bound on Rad. Complexity

Corollary: Let G be a family of functions taking values in $\{-1, +1\}$, then the following holds:

$$\Re_m(G) \le \sqrt{\frac{2\log \Pi_G(m)}{m}}.$$

$$\begin{aligned} \widehat{\mathfrak{R}}_{S}(G) &= \mathop{\mathrm{E}}_{\sigma} \left[\sup_{g \in G} \frac{1}{m} \begin{bmatrix} \sigma_{1} \\ \vdots \\ \sigma_{m} \end{bmatrix} \cdot \begin{bmatrix} g(z_{1}) \\ \vdots \\ g(z_{m}) \end{bmatrix} \right] \\ &\leq \frac{\sqrt{m}\sqrt{2\log|\{(g(z_{1}), \dots, g(z_{m})) \colon g \in G\}|}}{m} \quad \text{(Massart's Lemma)} \\ &\leq \frac{\sqrt{m}\sqrt{2\log\Pi_{G}(m)}}{m} = \sqrt{\frac{2\log\Pi_{G}(m)}{m}}. \end{aligned}$$

Generalization Bound - Growth Function

Corollary: Let H be a family of functions taking values in $\{-1, +1\}$. Then, for any $\delta > 0$, with probability at least $1-\delta$, for any $h \in H$,

$$R(h) \le \widehat{R}(h) + \sqrt{\frac{2\log \Pi_H(m)}{m}} + \sqrt{\frac{\log \frac{1}{\delta}}{2m}}.$$

But, how do we compute the growth function? Relationship with the VC-dimension (Vapnik-Chervonenkis dimension).

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VC Dimension

(Vapnik & Chervonenkis, 1968-1971; Vapnik, 1982, 1995, 1998)

Definition: the VC-dimension of a hypothesis set H is defined by

 $\operatorname{VCdim}(H) = \max\{m \colon \Pi_H(m) = 2^m\}.$

- Thus, the VC-dimension is the size of the largest set that can be fully shattered by H.
- Purely combinatorial notion.

Examples

- In the following, we determine the VC dimension for several hypothesis sets.
- To give a lower bound d for VCdim(H), it suffices to show that a set S of cardinality d can be shattered by H.
- To give an upper bound, we need to prove that no set S of cardinality d+1 can be shattered by H, which is typically more difficult.

Intervals of The Real Line

Observations:

- No set of three points can be shattered since the following dichotomy "+ - +" is not realizable (by definition of intervals):

• Thus, $VCdim(intervals in \mathbb{R}) = 2$.

Hyperplanes

Observations:

• Any three non-collinear points can be shattered:

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• Unrealizable dichotomies for four points:

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• Thus, VCdim(hyperplanes in \mathbb{R}^d) = d+1.

Axis-Aligned Rectangles in the Plane

Observations:

• The following four points can be shattered:



 No set of five points can be shattered: label negatively the point that is not near the sides.

• Thus, VCdim(axis-aligned rectangles) = 4.

Convex Polygons in the Plane

Observations:

• 2d+1 points on a circle can be shattered by a d-gon:





positive points| < |negative points|</pre>

|positive points| > |negative points|

It can be shown that choosing the points on the circle maximizes the number of possible dichotomies. Thus, VCdim(convex *d*-gons) = 2*d*+1.
 Also, VCdim(convex polygons) = +∞.

Sine Functions

Observations:

• Any finite set of points on the real line can be shattered by $\{t \mapsto \sin(\omega t) : \omega \in \mathbb{R}\}$.

• Thus, $VCdim(sine functions) = +\infty$.



Sauer's Lemma

(Vapnik & Chervonenkis, 1968-1971; Sauer, 1972)

Theorem: let H be a hypothesis set with VCdim(H) = dthen, for all $m \in \mathbb{N}$,

$$\Pi_H(m) \le \sum_{i=0}^d \binom{m}{i}.$$

- Proof: the proof is by induction on m+d. The statement clearly holds for m=1 and d=0 or d=1. Assume that it holds for (m-1, d-1) and (m-1, d).
 - Fix a set $S = \{x_1, \ldots, x_m\}$ with $\Pi_H(m)$ dichotomies and let $G = H_{|S}$ be the set of concepts H induces by restriction to S.

• Consider the following families over $S' = \{x_1, \ldots, x_{m-1}\}$:



• **Observe that** $|G_1| + |G_2| = |G|$.

• Since $\operatorname{VCdim}(G_1) \leq d$, by the induction hypothesis,

$$G_1 | \le \Pi_{G_1}(m-1) \le \sum_{i=0}^d \binom{m-1}{i}$$

• By definition of G_2 , if a set $Z \subseteq S'$ is shattered by G_2 , then the set $Z \cup \{x_m\}$ is shattered by G. Thus,

 $\operatorname{VCdim}(G_2) \leq \operatorname{VCdim}(G) - 1 = d - 1$

and by the induction hypothesis,

$$|G_2| \le \Pi_{G_2}(m-1) \le \sum_{i=0}^{d-1} \binom{m-1}{i}.$$

• Thus, $|G| \le \sum_{i=0}^d \binom{m-1}{i} + \sum_{i=0}^{d-1} \binom{m-1}{i}$
 $= \sum_{i=0}^d \binom{m-1}{i} + \binom{m-1}{i-1} = \sum_{i=0}^d \binom{m}{i}.$

Sauer's Lemma - Consequence

Corollary: let H be a hypothesis set with VCdim(H) = dthen, for all $m \ge d$,

$$\Pi_H(m) \le \left(\frac{em}{d}\right)^d = O(m^d).$$

Proof: $\sum_{i=0}^{d}$

$$\begin{split} \binom{m}{i} &\leq \sum_{i=0}^{d} \binom{m}{i} \left(\frac{m}{d}\right)^{d-i} \\ &\leq \sum_{i=0}^{m} \binom{m}{i} \left(\frac{m}{d}\right)^{d-i} \\ &= \left(\frac{m}{d}\right)^{d} \sum_{i=0}^{m} \binom{m}{i} \left(\frac{d}{m}\right)^{i} \\ &= \left(\frac{m}{d}\right)^{d} \left(1 + \frac{d}{m}\right)^{m} \leq \left(\frac{m}{d}\right)^{d} e^{d}. \end{split}$$

Remarks

- Remarkable property of growth function:
 - either $\operatorname{VCdim}(H) = d < +\infty$ and $\Pi_H(m) = O(m^d)$
 - or $\operatorname{VCdim}(H) = +\infty$ and $\Pi_H(m) = 2^m$.

Generalization Bound - VC Dimension

Corollary: Let H be a family of functions taking values in $\{-1, +1\}$ with VC dimension d. Then, for any $\delta > 0$, with probability at least $1 - \delta$, for any $h \in H$,

$$R(h) \le \widehat{R}(h) + \sqrt{\frac{2d\log\frac{em}{d}}{m}} + \sqrt{\frac{\log\frac{1}{\delta}}{2m}}.$$

Proof: Corollary combined with Sauer's lemma.
 Note: The general form of the result is

$$R(h) \le \widehat{R}(h) + O\left(\sqrt{\frac{\log(m/d)}{(m/d)}}\right)$$

Comparison - Standard VC Bound

(Vapnik & Chervonenkis, 1971; Vapnik, 1982)

Theorem: Let H be a family of functions taking values in $\{-1, +1\}$ with VC dimension d. Then, for any $\delta > 0$, with probability at least $1 - \delta$, for any $h \in H$,

$$R(h) \le \widehat{R}(h) + \sqrt{\frac{8d\log\frac{2em}{d} + 8\log\frac{4}{\delta}}{m}}$$

Proof: Derived from growth function bound

$$\Pr\left[\left|R(h) - \widehat{R}(h)\right| > \epsilon\right] \le 4\Pi_H(2m) \exp\left(-\frac{m\epsilon^2}{8}\right)$$

This lecture

- Rademacher complexity
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VCDim Lower Bound - Realizable Case

(Ehrenfeucht et al., 1988)

- Theorem: let H be a hypothesis set with VC dimension d > 1. Then, for any learning algorithm L, $\exists D, \exists f \in H, \Pr_{S \sim D^m} \left| R_D(h_S, f) > \frac{d-1}{32m} \right| \ge 1/100.$
- **Proof:** choose D such that L can do no better than tossing a coin for some points.
 - Let $X = \{x_0, x_1, \dots, x_{d-1}\}$ be a set fully shattered. For any $\epsilon > 0$, define D with support X by $\Pr_{D}[x_0] = 1 - 8\epsilon \quad \text{and} \quad \forall i \in [1, d-1] \; \Pr[x_i]$ 8ϵ

$$[\sigma] = 1 - 8\epsilon$$
 and $\forall i \in [1, d - 1], \Pr_D[x_i] = \frac{1}{d - 1}$

- We can assume without loss of generality that L makes no error on x_0 .
- For a sample S, let \overline{S} denote the set of its elements falling in $X_1 = \{x_1, \dots, x_{d-1}\}$ and let S be the set of samples of size m with at most (d-1)/2 points in X_1 .
- Fix a sample $S \in S$. Using $|X \overline{S}| \ge (d 1)/2$,

$$\begin{split} \mathop{\mathrm{E}}_{f\sim U}[R_D(h_S, f)] &= \sum_f \sum_{x\in X} 1_{h(x)\neq f(x)} \Pr[x] \Pr[f] \\ &\geq \sum_f \sum_{x\notin \overline{S}} 1_{h(x)\neq f(x)} \Pr[x] \Pr[f] \\ &= \sum_{x\notin \overline{S}} \left(\sum_f 1_{h(x)\neq f(x)} \Pr[f] \right) \Pr[x] \\ &= \frac{1}{2} \sum_{x\notin \overline{S}} \Pr[x] \geq \frac{1}{2} \frac{d-1}{2} \frac{8\epsilon}{d-1} = 2\epsilon. \end{split}$$

- Since the inequality holds for all $S \in S$, it also holds in expectation: $E_{S,f\sim U}[R_D(h_S, f)] \ge 2\epsilon$. This implies that there exists a labeling f_0 such that $E_S[R_D(h_S, f_0)] \ge 2\epsilon$.
- Since $\Pr_D[X \{x_0\}] \leq 8\epsilon$, we also have $R_D(h_S, f_0) \leq 8\epsilon$. Thus,

 $2\epsilon \leq \mathop{\mathrm{E}}_{S}[R_D(h_S, f_0)] \leq 8\epsilon \mathop{\mathrm{Pr}}_{S \in \mathcal{S}}[R_D(h_S, f_0) \geq \epsilon] + (1 - \mathop{\mathrm{Pr}}_{S \in \mathcal{S}}[R_D(h_S, f_0) \geq \epsilon])\epsilon.$

- Collecting terms $\inf_{S \in \mathcal{S}} [R_D(h_S, f_0) \ge \epsilon]$, we obtain: $\Pr_{S \in \mathcal{S}} [R_D(h_S, f_0) \ge \epsilon] \ge \frac{1}{7\epsilon} (2\epsilon - \epsilon) = \frac{1}{7}.$
- Thus, the probability over all samples S (not necessarily in S) can be lower bounded as

$$\Pr_{S}[R_{D}(h_{S}, f_{0}) \ge \epsilon] \ge \Pr_{S \in \mathcal{S}}[R_{D}(h_{S}, f_{0}) \ge \epsilon] \Pr[\mathcal{S}] \ge \frac{1}{7} \Pr[\mathcal{S}].$$

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 This leads us to seeking a lower bound for Pr[S]. The probability that more than (d - 1)/2 points be drawn in a sample of size m verifies the Chernoff bound for any γ > 0:

$$1 - \Pr[\mathcal{S}] = \Pr[S_m \ge 8\epsilon m(1+\gamma)] \le e^{-8\epsilon m\frac{\gamma^2}{3}}.$$

• Thus, for $\epsilon = (d-1)/(32m)$ and $\gamma = 1$,

$$\Pr[S_m \ge \frac{d-1}{2}] \le e^{-(d-1)/12} \le e^{-1/12} \le 1 - 7\delta,$$

for $\delta \leq .01$. Thus, $\Pr[\mathcal{S}] \geq 7\delta$ and

$$\Pr_{S}[R_D(h_S, f_0) \ge \epsilon] \ge \delta.$$

Agnostic PAC Model

- Definition: concept class C is PAC-learnable if there exists a learning algorithm L such that:
 - for all $c \in C, \epsilon > 0, \delta > 0$, and all distributions D,

$$\Pr_{S \sim D} \left[R(h_S) - \inf_{h \in H} R(h) \le \epsilon \right] \ge 1 - \delta,$$

• for samples S of size $m = poly(1/\epsilon, 1/\delta)$ for a fixed polynomial.

VCDim Lower Bound - Non-Realizable Case

(Anthony and Bartlett, 1999)

- Theorem: let *H* be a hypothesis set with VC dimension d > 1. Then, for any learning algorithm *L*, $\exists D \text{ over } X \times \{0, 1\},$ $\Pr_{S \sim D^m} \left[R_D(h_S) - \inf_{h \in H} R_D(h) > \sqrt{\frac{d}{320m}} \right] \ge 1/64.$
- Equivalently, for any learning algorithm, the sample complexity verifies

$$m \ge \frac{d}{320\epsilon^2}.$$

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