

Foundations of Machine Learning

Support Vector Machines

Binary Classification Problem

- **Training data:** sample drawn i.i.d. from set $X \subseteq \mathbb{R}^N$ according to some distribution D ,

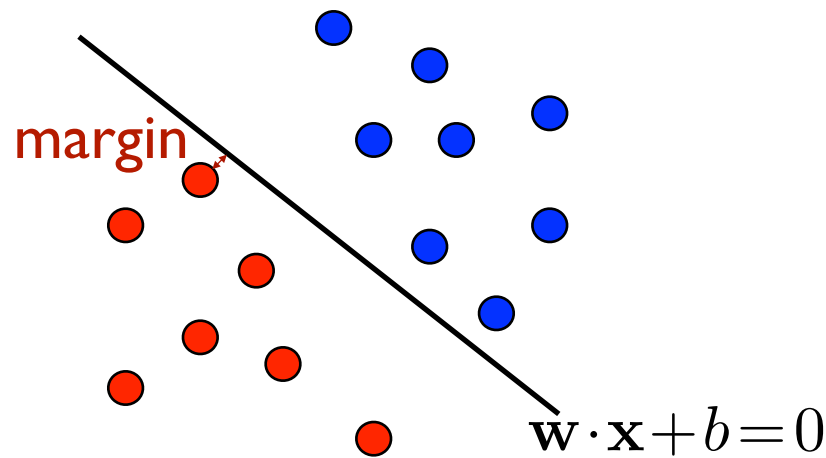
$$S = ((x_1, y_1), \dots, (x_m, y_m)) \in X \times \{-1, +1\}.$$

- **Problem:** find hypothesis $h: X \mapsto \{-1, +1\}$ in H (classifier) with small generalization error $R(h)$.
- choice of hypothesis set H : learning guarantees of previous lecture.
 - ➔ linear classification (hyperplanes) if dimension N is not too large.

This Lecture

- Support Vector Machines - separable case
- Support Vector Machines - non-separable case
- Margin guarantees

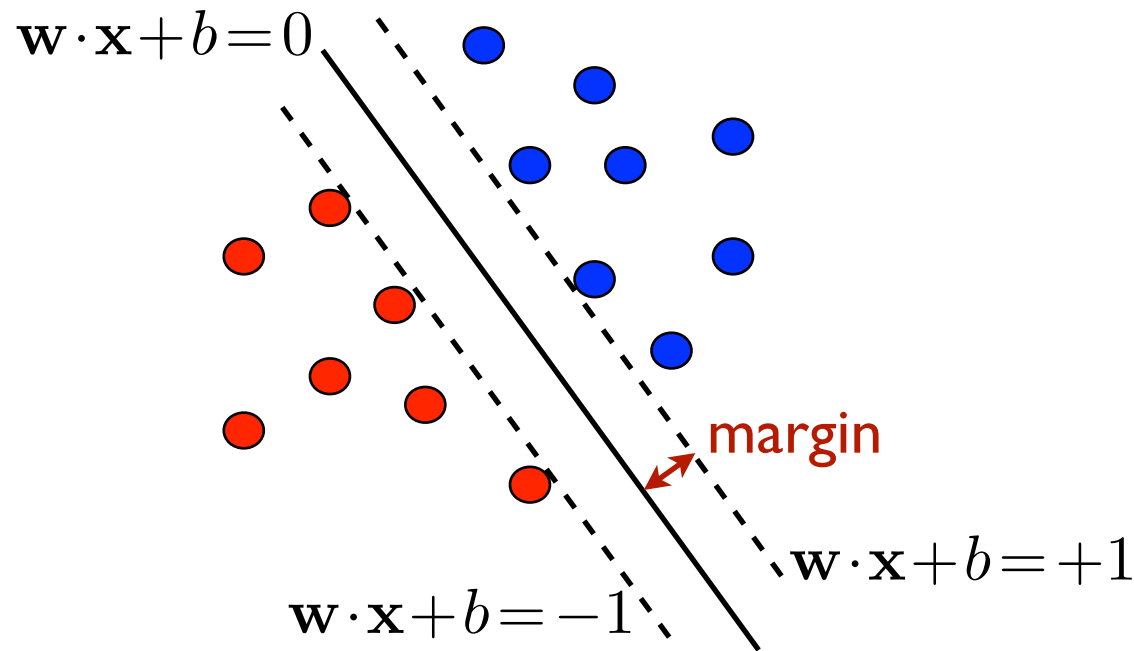
Linear Separation



- classifiers: $H = \{\mathbf{x} \mapsto \text{sgn}(\mathbf{w} \cdot \mathbf{x} + b) : \mathbf{w} \in \mathbb{R}^N, b \in \mathbb{R}\}$.
- geometric margin: $\rho = \min_{i \in [1, m]} \frac{|\mathbf{w} \cdot \mathbf{x}_i + b|}{\|\mathbf{w}\|}$.
- which separating hyperplane?

Optimal Hyperplane: Max. Margin

(Vapnik and Chervonenkis, 1965)



$$\rho = \max_{\mathbf{w}, b : y_i(\mathbf{w} \cdot \mathbf{x}_i + b) \geq 0} \min_{i \in [1, m]} \frac{|\mathbf{w} \cdot \mathbf{x}_i + b|}{\|\mathbf{w}\|}.$$

Maximum Margin

$$\begin{aligned}\rho &= \max_{\mathbf{w}, b: y_i(\mathbf{w} \cdot \mathbf{x}_i + b) \geq 0} \min_{i \in [1, m]} \frac{|\mathbf{w} \cdot \mathbf{x}_i + b|}{\|\mathbf{w}\|} \\&= \max_{\substack{\mathbf{w}, b: y_i(\mathbf{w} \cdot \mathbf{x}_i + b) \geq 0 \\ \min_{i \in [1, m]} |\mathbf{w} \cdot \mathbf{x}_i + b| = 1}} \min_{i \in [1, m]} \frac{|\mathbf{w} \cdot \mathbf{x}_i + b|}{\|\mathbf{w}\|} \quad (\text{scale-invariance}) \\&= \max_{\substack{\mathbf{w}, b: y_i(\mathbf{w} \cdot \mathbf{x}_i + b) \geq 0 \\ \min_{i \in [1, m]} |\mathbf{w} \cdot \mathbf{x}_i + b| = 1}} \frac{1}{\|\mathbf{w}\|} \\&= \max_{\mathbf{w}, b: y_i(\mathbf{w} \cdot \mathbf{x}_i + b) \geq 1} \frac{1}{\|\mathbf{w}\|}. \quad (\text{min. reached})\end{aligned}$$

Optimization Problem

■ Constrained optimization:

$$\min_{\mathbf{w}, b} \frac{1}{2} \|\mathbf{w}\|^2$$

subject to $y_i(\mathbf{w} \cdot \mathbf{x}_i + b) \geq 1, i \in [1, m]$.

■ Properties:

- Convex optimization.
- Unique solution for linearly separable sample.

Optimal Hyperplane Equations

■ **Lagrangian:** for all $\mathbf{w}, b, \alpha_i \geq 0$,

$$L(\mathbf{w}, b, \alpha) = \frac{1}{2} \|\mathbf{w}\|^2 - \sum_{i=1}^m \alpha_i [y_i(\mathbf{w} \cdot \mathbf{x}_i + b) - 1].$$

■ **KKT conditions:**

$$\begin{aligned} \nabla_{\mathbf{w}} L &= \mathbf{w} - \sum_{i=1}^m \alpha_i y_i \mathbf{x}_i = 0 \iff \mathbf{w} = \sum_{i=1}^m \alpha_i y_i \mathbf{x}_i. \\ \nabla_b L &= - \sum_{i=1}^m \alpha_i y_i = 0 \iff \sum_{i=1}^m \alpha_i y_i = 0. \end{aligned}$$

$$\forall i \in [1, m], \alpha_i [y_i(\mathbf{w} \cdot \mathbf{x}_i + b) - 1] = 0.$$

Support Vectors

- Complementarity conditions:

$$\alpha_i [y_i(\mathbf{w} \cdot \mathbf{x}_i + b) - 1] = 0 \implies \alpha_i = 0 \vee y_i(\mathbf{w} \cdot \mathbf{x}_i + b) = 1.$$

- **Support vectors:** vectors $\mathbf{x}_i$ such that

$$\alpha_i \neq 0 \wedge y_i(\mathbf{w} \cdot \mathbf{x}_i + b) = 1.$$

- Note: support vectors are not unique.

Moving to The Dual

- Plugging in the expression of w in L gives:

$$L = \underbrace{\frac{1}{2} \left\| \sum_{i=1}^m \alpha_i y_i \mathbf{x}_i \right\|^2 - \sum_{i,j=1}^m \alpha_i \alpha_j y_i y_j (\mathbf{x}_i \cdot \mathbf{x}_j)}_{-\frac{1}{2} \sum_{i,j=1}^m \alpha_i \alpha_j y_i y_j (\mathbf{x}_i \cdot \mathbf{x}_j)} - \underbrace{\sum_{i=1}^m \alpha_i y_i b}_0 + \sum_{i=1}^m \alpha_i.$$

- Thus,

$$L = \sum_{i=1}^m \alpha_i - \frac{1}{2} \sum_{i,j=1}^m \alpha_i \alpha_j y_i y_j (\mathbf{x}_i \cdot \mathbf{x}_j).$$

Equivalent Dual Opt. Problem

■ Constrained optimization:

$$\max_{\alpha} \sum_{i=1}^m \alpha_i - \frac{1}{2} \sum_{i,j=1}^m \alpha_i \alpha_j y_i y_j (\mathbf{x}_i \cdot \mathbf{x}_j)$$

$$\text{subject to: } \alpha_i \geq 0 \wedge \sum_{i=1}^m \alpha_i y_i = 0, i \in [1, m].$$

■ Solution:

$$h(x) = \text{sgn}\left(\sum_{i=1}^m \alpha_i y_i (\mathbf{x}_i \cdot \mathbf{x}) + b\right),$$

$$\text{with } b = y_i - \sum_{j=1}^m \alpha_j y_j (\mathbf{x}_j \cdot \mathbf{x}_i) \text{ for any SV } \mathbf{x}_i.$$

Leave-One-Out Error

- **Definition:** let h_S be the hypothesis output by learning algorithm L after receiving sample S of size m . Then, the **leave-one-out error** of L over S is:

$$\hat{R}_{\text{loo}}(L) = \frac{1}{m} \sum_{i=1}^m 1_{h_{S-\{x_i\}}(x_i) \neq f(x_i)}.$$

- **Property:** unbiased estimate of expected error of hypothesis trained on sample of size $m-1$,

$$\begin{aligned} \boxed{\mathbb{E}_{S \sim D^m} [\hat{R}_{\text{loo}}(L)]} &= \frac{1}{m} \sum_{i=1}^m \mathbb{E}_S [1_{h_{S-\{x_i\}}(x_i) \neq f(x_i)}] = \mathbb{E}_S [1_{h_{S-\{x\}}(x) \neq f(x)}] \\ &= \mathbb{E}_{S' \sim D^{m-1}} [\mathbb{E}_{x \sim D} [1_{h_{S'}(x) \neq f(x)}]] = \boxed{\mathbb{E}_{S' \sim D^{m-1}} [R(h_{S'})]}. \end{aligned}$$

Leave-One-Out Analysis

- **Theorem:** let h_S be the optimal hyperplane for a sample S and let $N_{SV}(S)$ be the number of support vectors defining h_S . Then,

$$\mathbb{E}_{S \sim D^m} [R(h_S)] \leq \mathbb{E}_{S \sim D^{m+1}} \left[\frac{N_{SV}(S)}{m+1} \right].$$

- **Proof:** Let $S \sim D^{m+1}$ be a sample linearly separable and let $x \in S$. If $h_{S-\{x\}}$ misclassifies x , then x must be a SV for h_S . Thus,

$$\hat{R}_{loo}(\text{opt.-hyp.}) \leq \frac{N_{SV}(S)}{m+1}.$$

Notes

- Bound on expectation of error only, not the probability of error.
- Argument based on **sparsity** (number of support vectors). We will see later other arguments in support of the optimal hyperplanes based on the concept of **margin**.

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- Support Vector Machines - non-separable case
- Margin guarantees

Support Vector Machines

(Cortes and Vapnik, 1995)

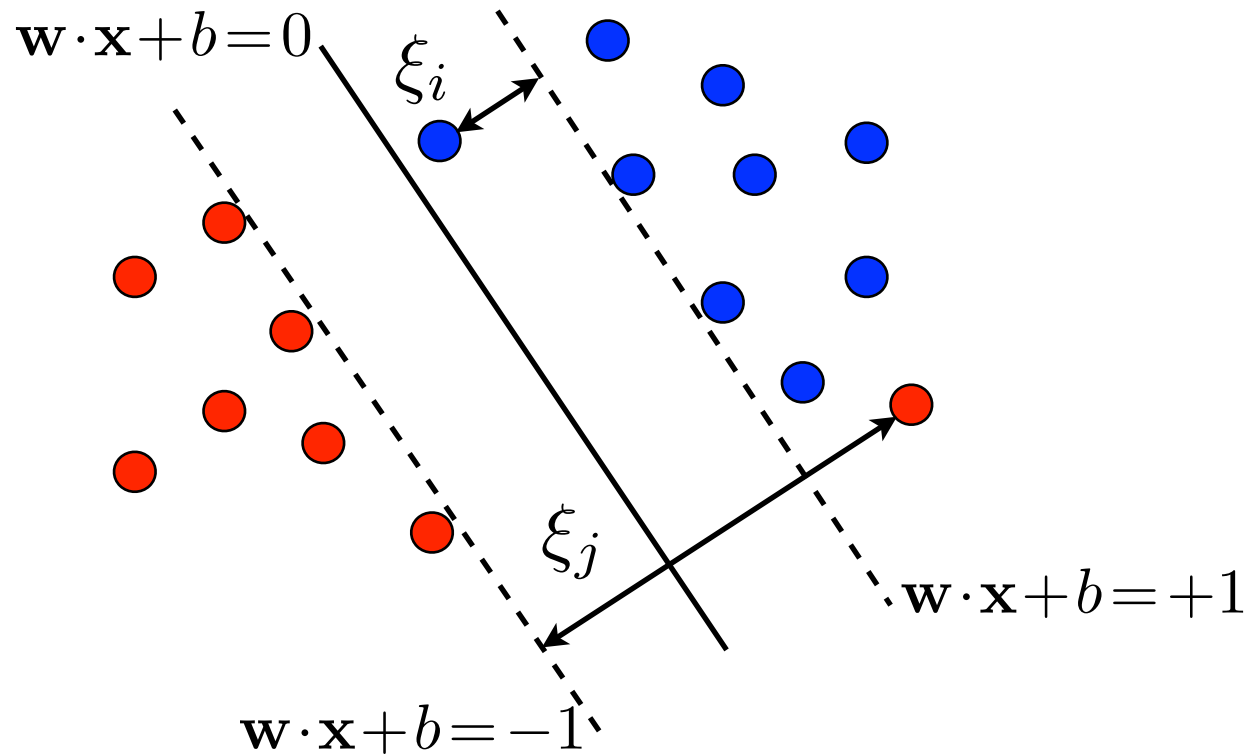
- **Problem:** data often not linearly separable in practice. For any hyperplane, there exists $\mathbf{x}_i$ such that

$$y_i [\mathbf{w} \cdot \mathbf{x}_i + b] \not\geq 1.$$

- **Idea:** relax constraints using **slack variables** $\xi_i \geq 0$

$$y_i [\mathbf{w} \cdot \mathbf{x}_i + b] \geq 1 - \xi_i.$$

Soft-Margin Hyperplanes



- **Support vectors:** points along the margin or outliers.
- **Soft margin:** $\rho = 1/\|\mathbf{w}\|$.

Optimization Problem

(Cortes and Vapnik, 1995)

■ Constrained optimization:

$$\min_{\mathbf{w}, b, \xi} \quad \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{i=1}^m \xi_i$$

subject to $y_i(\mathbf{w} \cdot \mathbf{x}_i + b) \geq 1 - \xi_i \quad \wedge \quad \xi_i \geq 0, i \in [1, m]$.

■ Properties:

- $C \geq 0$ trade-off parameter.
- Convex optimization.
- Unique solution.

Notes

- Parameter C : trade-off between maximizing margin and minimizing training error. How do we determine C ?
- The general problem of determining a hyperplane minimizing the error on the training set is NP-complete (as a function of the dimension).
- Other convex functions of the slack variables could be used: this choice and a similar one with squared slack variables lead to a convenient formulation and solution.

SVM - Equivalent Problem

■ Optimization:

$$\min_{\mathbf{w}, b} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{i=1}^m \left(1 - y_i(\mathbf{w} \cdot \mathbf{x}_i + b)\right)_+.$$

■ Loss functions:

- hinge loss:

$$L(h(x), y) = (1 - yh(x))_+.$$

- quadratic hinge loss:

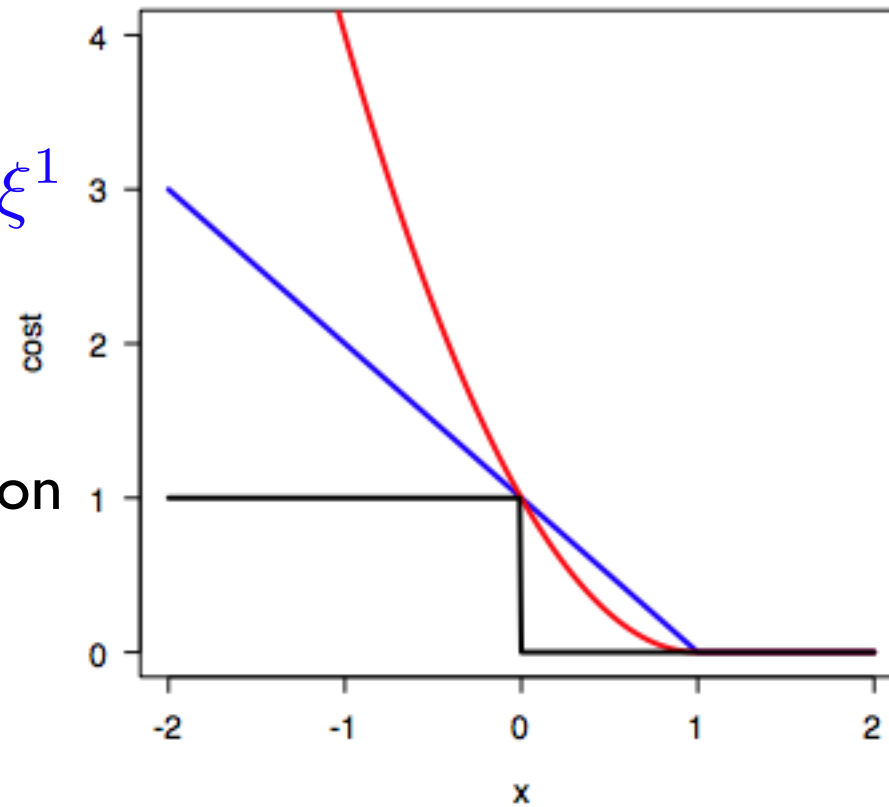
$$L(h(x), y) = (1 - yh(x))_+^2.$$

Hinge Loss

'Quadratic' hinge loss ξ^2

Hinge loss ξ^1

0/1 loss function



SVMs Equations

■ **Lagrangian:** for all $\mathbf{w}, b, \alpha_i \geq 0, \beta_i \geq 0$,

$$L(\mathbf{w}, b, \boldsymbol{\xi}, \boldsymbol{\alpha}, \boldsymbol{\beta}) = \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{i=1}^m \xi_i - \sum_{i=1}^m \alpha_i [y_i(\mathbf{w} \cdot \mathbf{x}_i + b) - 1 + \xi_i] - \sum_{i=1}^m \beta_i \xi_i.$$

■ **KKT conditions:**

$$\begin{aligned} \nabla_{\mathbf{w}} L &= \mathbf{w} - \sum_{i=1}^m \alpha_i y_i \mathbf{x}_i = 0 &\iff \mathbf{w} &= \sum_{i=1}^m \alpha_i y_i \mathbf{x}_i. \\ \nabla_b L &= - \sum_{i=1}^m \alpha_i y_i = 0 &\iff \sum_{i=1}^m \alpha_i y_i &= 0. \\ \nabla_{\xi_i} L &= C - \alpha_i - \beta_i = 0 &\iff \alpha_i + \beta_i &= C. \end{aligned}$$

$$\forall i \in [1, m], \alpha_i [y_i(\mathbf{w} \cdot \mathbf{x}_i + b) - 1 + \xi_i] = 0$$

$$\beta_i \xi_i = 0.$$

Support Vectors

■ Complementarity conditions:

$$\alpha_i [y_i(\mathbf{w} \cdot \mathbf{x}_i + b) - 1 + \xi_i] = 0 \implies \alpha_i = 0 \vee y_i(\mathbf{w} \cdot \mathbf{x}_i + b) = 1 - \xi_i.$$

■ Support vectors: vectors $\mathbf{x}_i$ such that

$$\alpha_i \neq 0 \wedge y_i(\mathbf{w} \cdot \mathbf{x}_i + b) = 1 - \xi_i.$$

- Note: support vectors are not unique.

Moving to The Dual

- Plugging in the expression of w in L gives:

$$L = \underbrace{\frac{1}{2} \left\| \sum_{i=1}^m \alpha_i y_i \mathbf{x}_i \right\|^2 - \sum_{i,j=1}^m \alpha_i \alpha_j y_i y_j (\mathbf{x}_i \cdot \mathbf{x}_j)}_{-\frac{1}{2} \sum_{i,j=1}^m \alpha_i \alpha_j y_i y_j (\mathbf{x}_i \cdot \mathbf{x}_j)} - \underbrace{\sum_{i=1}^m \alpha_i y_i b}_{0} + \sum_{i=1}^m \alpha_i.$$

- Thus,

$$L = \sum_{i=1}^m \alpha_i - \frac{1}{2} \sum_{i,j=1}^m \alpha_i \alpha_j y_i y_j (\mathbf{x}_i \cdot \mathbf{x}_j).$$

- The condition $\beta_i \geq 0$ is equivalent to $\alpha_i \leq C$.

Dual Optimization Problem

■ Constrained optimization:

$$\max_{\alpha} \sum_{i=1}^m \alpha_i - \frac{1}{2} \sum_{i,j=1}^m \alpha_i \alpha_j y_i y_j (\mathbf{x}_i \cdot \mathbf{x}_j)$$

$$\text{subject to: } 0 \leq \alpha_i \leq C \wedge \sum_{i=1}^m \alpha_i y_i = 0, i \in [1, m].$$

■ Solution:

$$h(x) = \text{sgn}\left(\sum_{i=1}^m \alpha_i y_i (\mathbf{x}_i \cdot \mathbf{x}) + b\right),$$

$$\text{with } b = y_i - \sum_{j=1}^m \alpha_j y_j (\mathbf{x}_j \cdot \mathbf{x}_i) \text{ for any } \mathbf{x}_i \text{ with } 0 < \alpha_i < C.$$

This Lecture

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High-Dimension

- Learning guarantees: for hyperplanes in dimension N with probability at least $1 - \delta$,

$$R(h) \leq \hat{R}(h) + \sqrt{\frac{2(N+1) \log \frac{em}{N+1}}{m}} + \sqrt{\frac{\log \frac{1}{\delta}}{2m}}.$$

- bound is uninformative for $N \gg m$.
- but SVMs have been remarkably successful in high-dimension.
- can we provide a theoretical justification?
- analysis of underlying scoring function.

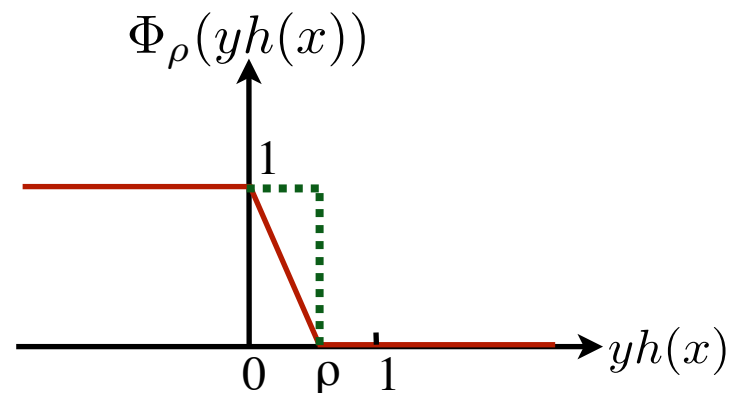
Confidence Margin

- **Definition:** the confidence margin of a real-valued function h at $(x, y) \in X \times Y$ is $\rho_h(x, y) = yh(x)$.
 - interpreted as the hypothesis' confidence in prediction.
 - if correctly classified coincides with $|h(x)|$.
 - relationship with geometric margin for linear functions $h: \mathbf{x} \mapsto \mathbf{w} \cdot \mathbf{x} + b$: for x in the sample,

$$|\rho_h(x, y)| \geq \rho_{\text{geom}} \|\mathbf{w}\|.$$

Confidence Margin Loss

- **Definition:** for any confidence margin parameter $\rho > 0$ the ρ -margin loss function Φ_ρ is defined by



- For a sample $S = (x_1, \dots, x_m)$ and real-valued hypothesis h , the empirical margin loss is

$$\hat{R}_\rho(h) = \frac{1}{m} \sum_{i=1}^m \Phi_\rho(y_i h(x_i)) \leq \frac{1}{m} \sum_{i=1}^m 1_{y_i h(x_i) < \rho}$$

General Margin Bound

- **Theorem:** Let H be a set of real-valued functions. Fix $\rho > 0$. For any $\delta > 0$, with probability at least $1 - \delta$, the following holds for all $h \in H$:

$$R(h) \leq \hat{R}_\rho(h) + \frac{2}{\rho} \mathfrak{R}_m(H) + \sqrt{\frac{\log \frac{1}{\delta}}{2m}}$$

$$R(h) \leq \hat{R}_\rho(h) + \frac{2}{\rho} \hat{\mathfrak{R}}_S(H) + 3\sqrt{\frac{\log \frac{2}{\delta}}{2m}}.$$

- **Proof:** Let $\tilde{H} = \{z = (x, y) \mapsto yh(x) : h \in H\}$. Consider the family of functions taking values in $[0, 1]$:

$$\tilde{\mathcal{H}} = \{\Phi_\rho \circ f : f \in \tilde{H}\}.$$

- By the theorem of Lecture 3, with probability at least $1 - \delta$, for all $g \in \tilde{\mathcal{H}}$,

$$\mathbb{E}[g(z)] \leq \frac{1}{m} \sum_{i=1}^m g(z_i) + 2\mathfrak{R}_m(\tilde{\mathcal{H}}) + \sqrt{\frac{\log \frac{1}{\delta}}{2m}}.$$

- Thus,

$$\mathbb{E}[\Phi_\rho(yh(x))] \leq \hat{R}_\rho(h) + 2\mathfrak{R}_m(\Phi_\rho \circ \tilde{H}) + \sqrt{\frac{\log \frac{1}{\delta}}{2m}}.$$

- Since Φ_ρ is $\frac{1}{\rho}$ - Lipschitz, by Talagrand's lemma,

$$\mathfrak{R}_m(\Phi_\rho \circ \tilde{H}) \leq \frac{1}{\rho} \mathfrak{R}_m(\tilde{H}) = \frac{1}{\rho m} \mathbb{E}_{\sigma, S} \left[\sup_{h \in H} \sum_{i=1}^m \sigma_i y_i h(x_i) \right] = \frac{1}{\rho} \mathfrak{R}_m(H).$$

- Since $1_{yh(x) < 0} \leq \Phi_\rho(yh(x))$, this shows the first statement, and similarly the second one.

Rademacher Complexity of Linear Hypotheses

■ **Theorem:** Let $S \subseteq \{x : \|\mathbf{x}\| \leq R\}$ be a sample of size m and let $H = \{\mathbf{x} \mapsto \mathbf{w} \cdot \mathbf{x} : \|\mathbf{w}\| \leq \Lambda\}$. Then,

$$\hat{\mathfrak{R}}_S(H) \leq \sqrt{\frac{R^2 \Lambda^2}{m}}.$$

■ **Proof:**

$$\begin{aligned} \hat{\mathfrak{R}}_S(H) &= \frac{1}{m} \mathbb{E}_{\sigma} \left[\sup_{\|\mathbf{w}\| \leq \Lambda} \sum_{i=1}^m \sigma_i \mathbf{w} \cdot \mathbf{x}_i \right] = \frac{1}{m} \mathbb{E}_{\sigma} \left[\sup_{\|\mathbf{w}\| \leq \Lambda} \mathbf{w} \cdot \sum_{i=1}^m \sigma_i \mathbf{x}_i \right] \\ &\leq \frac{\Lambda}{m} \mathbb{E}_{\sigma} \left[\left\| \sum_{i=1}^m \sigma_i \mathbf{x}_i \right\| \right] \leq \frac{\Lambda}{m} \left[\mathbb{E}_{\sigma} \left[\left\| \sum_{i=1}^m \sigma_i \mathbf{x}_i \right\|^2 \right] \right]^{1/2} \\ &\leq \frac{\Lambda}{m} \left[\mathbb{E}_{\sigma} \left[\sum_{i=1}^m \|\mathbf{x}_i\|^2 \right] \right]^{1/2} \leq \frac{\Lambda \sqrt{m R^2}}{m} = \sqrt{\frac{R^2 \Lambda^2}{m}}. \end{aligned}$$

Margin Bound - Linear Classifiers

- **Corollary:** Let $\rho > 0$ and $H = \{\mathbf{x} \mapsto \mathbf{w} \cdot \mathbf{x} : \|\mathbf{w}\| \leq \Lambda\}$. Assume that $X \subseteq \{\mathbf{x} : \|\mathbf{x}\| \leq R\}$. Then, for any $\delta > 0$, with probability at least $1 - \delta$, for any $h \in H$,

$$R(h) \leq \hat{R}_\rho(h) + 2\sqrt{\frac{R^2 \Lambda^2 / \rho^2}{m}} + 3\sqrt{\frac{\log \frac{2}{\delta}}{2m}}.$$

- **Proof:** Follows directly general margin bound and bound on $\hat{\mathfrak{R}}_S(H)$ for linear classifiers.

High-Dimensional Feature Space

■ Observations:

- generalization bound does not depend on the dimension but on the margin.
- this suggests seeking a large-margin hyperplane in a higher-dimensional feature space.

■ Computational problems:

- taking dot products in a high-dimensional feature space can be very costly.
- solution based on **kernels** (next lecture).

References

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- Vladimir N. Vapnik. *Statistical Learning Theory*. Wiley-Interscience, New York, 1998.

Appendix

Saddle Point

- Let $(\mathbf{w}^*, b^*, \alpha^*)$ be the saddle point of the Lagrangian. Multiplying both sides of the equation giving b^* by $\alpha_i^* y_i$ and taking the sum leads to:

$$\sum_{i=1}^m \alpha_i^* y_i b^* = \sum_{i=1}^m \alpha_i^* y_i^2 - \sum_{i,j=1}^m \alpha_i^* \alpha_j^* y_i y_j (\mathbf{x}_i \cdot \mathbf{x}_j).$$

- Using $y_i^2 = 1$, $\sum_{i=1}^m \alpha_i^* y_i = 0$, and $\mathbf{w}^* = \sum_{i=1}^m \alpha_i^* y_i \mathbf{x}_i$ yields

$$0 = \sum_{i=1}^m \alpha_i^* - \|\mathbf{w}^*\|^2.$$

- Thus, the margin is also given by:

$$\rho^2 = \frac{1}{\|\mathbf{w}^*\|_2^2} = \frac{1}{\|\alpha^*\|_1}.$$

Talagrand's Contraction Lemma

(Ledoux and Talagrand, 1991; pp. 112-114)

■ **Theorem:** Let $\Phi: \mathbb{R} \rightarrow \mathbb{R}$ be an L -Lipschitz function. Then, for any hypothesis set H of real-valued functions,

$$\hat{\mathfrak{R}}_S(\Phi \circ H) \leq L \hat{\mathfrak{R}}_S(H).$$

■ **Proof:** fix sample $S = (x_1, \dots, x_m)$. By definition,

$$\begin{aligned} \mathfrak{R}_S(\Phi \circ H) &= \frac{1}{m} \mathbb{E}_{\sigma} \left[\sup_{h \in H} \sum_{i=1}^m \sigma_i(\Phi \circ h)(x_i) \right] \\ &= \frac{1}{m} \mathbb{E}_{\sigma_1, \dots, \sigma_{m-1}} \left[\mathbb{E}_{\sigma_m} \left[\sup_{h \in H} u_{m-1}(h) + \sigma_m(\Phi \circ h)(x_m) \right] \right], \end{aligned}$$

with $u_{m-1}(h) = \sum_{i=1}^{m-1} \sigma_i(\Phi \circ h)(x_i).$

Talagrand's Contraction Lemma

■ Now, assuming that the suprema are reached, there exist $h_1, h_2 \in H$ such that

$$\begin{aligned} & \mathbb{E}_{\sigma_m} \left[\sup_{h \in H} u_{m-1}(h) + \sigma_m(\Phi \circ h)(x_m) \right] \\ &= \frac{1}{2} [u_{m-1}(h_1) + (\Phi \circ h_1)(x_m)] + \frac{1}{2} [u_{m-1}(h_2) - (\Phi \circ h_2)(x_m)] \\ &\leq \frac{1}{2} [u_{m-1}(h_1) + u_{m-1}(h_2) + sL(h_1(x_m) - h_2(x_m))] \\ &= \frac{1}{2} [u_{m-1}(h_1) + sLh_1(x_m)] + \frac{1}{2} [u_{m-1}(h_2) - sLh_2(x_m)] \\ &\leq \mathbb{E}_{\sigma_m} \left[\sup_{h \in H} u_{m-1}(h) + \sigma_m Lh(x_m) \right], \end{aligned}$$

where $s = \text{sgn}(h_1(x_m) - h_2(x_m))$.

Talagrand's Contraction Lemma

- When the suprema are not reached, the same can be shown modulo ϵ , followed by $\epsilon \rightarrow 0$.
- Proceeding similarly for other σ_i s directly leads to the result.

VC Dimension of Canonical Hyperplanes

■ **Theorem:** Let $S \subseteq \{\mathbf{x} : \|\mathbf{x}\| \leq R\}$. Then, the VC dimension d of the set of canonical hyperplanes $\{x \mapsto \text{sgn}(\mathbf{w} \cdot \mathbf{x}) : \min_{x \in S} |\mathbf{w} \cdot \mathbf{x}| = 1 \wedge \|\mathbf{w}\| \leq \Lambda\}$ verifies

$$d \leq R^2 \Lambda^2.$$

■ **Proof:** Let $\{\mathbf{x}_1, \dots, \mathbf{x}_d\}$ be a set fully shattered. Then, for all $\mathbf{y} \in \{-1, +1\}^d$, there exists $\mathbf{w}$ such

$$\forall i \in [1, d], 1 \leq y_i(\mathbf{w} \cdot \mathbf{x}_i).$$

- Summing up the inequalities gives

$$d \leq \mathbf{w} \cdot \sum_{i=1}^d y_i \mathbf{x}_i \leq \|\mathbf{w}\| \left\| \sum_{i=1}^d y_i \mathbf{x}_i \right\| \leq \Lambda \left\| \sum_{i=1}^d y_i \mathbf{x}_i \right\|.$$

- Taking the expectation over $\mathbf{y} \sim U$ (uniform) yields

$$\begin{aligned} d &\leq \Lambda \mathbb{E}_{\mathbf{y} \sim U} \left[\left\| \sum_{i=1}^d y_i \mathbf{x}_i \right\| \right] \leq \Lambda \left[\mathbb{E}_{\mathbf{y} \sim U} \left[\left\| \sum_{i=1}^d y_i \mathbf{x}_i \right\|^2 \right] \right]^{1/2} \text{ (Jensen's ineq.)} \\ &= \Lambda \left[\sum_{i,j=1}^d \mathbb{E}[y_i y_j] (\mathbf{x}_i \cdot \mathbf{x}_j) \right]^{1/2} \\ &= \Lambda \left[\sum_{i=1}^d (\mathbf{x}_i \cdot \mathbf{x}_i) \right]^{1/2} \leq \Lambda [dR^2]^{1/2} = \Lambda R \sqrt{d}. \end{aligned}$$

- Thus, $\sqrt{d} \leq \Lambda R$.