Imperfect-Information, Extensive-Form Games



Imperfect Information

- Up until this point, we've assumed players know exactly which node of the game tree they're in
- Meaning: they have perfect recall of all actions played, including all other players.
- Want to represent two choices made in ignorance of one another



Imperfect Information

• Partition the nodes into "information sets", where a player cannot distinguish between two nodes in the same set



Imperfect Information

• Partition the nodes into "information sets", where a player cannot distinguish between two nodes in the same set

Definition 5.2.1 (Imperfect-information game) An imperfect-information game (in extensive form) is a tuple $(N, A, H, Z, \chi, \rho, \sigma, u, I)$, where:

- $(N, A, H, Z, \chi, \rho, \sigma, u)$ is a perfect-information extensive-form game; and
- $I = (I_1, \ldots, I_n)$, where $I_i = (I_{i,1}, \ldots, I_{i,k_i})$ is a set of equivalence classes on (i.e., a partition of) $\{h \in H : \rho(h) = i\}$ with the property that $\chi(h) = \chi(h')$ and $\rho(h) = \rho(h')$ whenever there exists a j for which $h \in I_{i,j}$ and $h' \in I_{i,j}$.



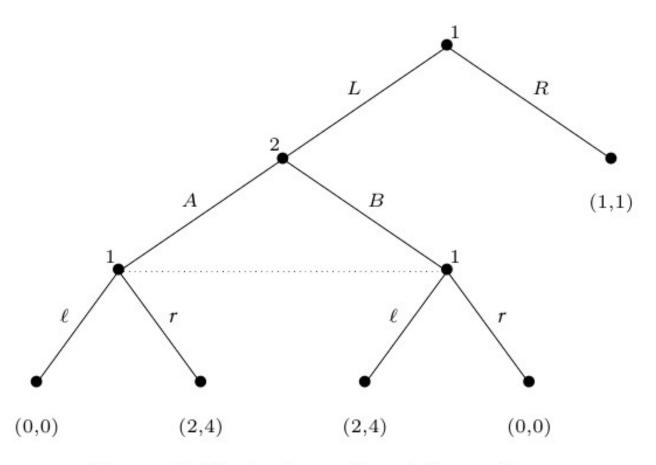


Figure 5.10: An imperfect-information game.



Imperfect-Information, Extensive-Form Games: Strategies and Equilibria



Pure Strategies

Definition 5.2.2 (Pure strategies) Let $G = (N, A, H, Z, \chi, \rho, \sigma, u, I)$ be an imperfect-information extensive-form game. Then the pure strategies of player i consist of the Cartesian product $\prod_{I_{i,j} \in I_i} \chi(I_{i,j})$.



Normal-Form to Extensive-Form

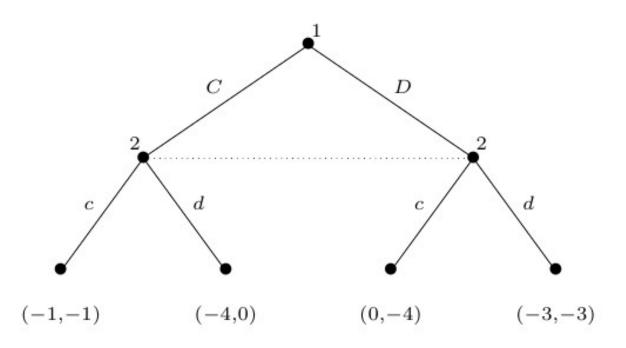


Figure 5.11: The Prisoner's Dilemma game in extensive form.



Mixed Strategies

- Transform extensive-form game into normal-form (enumerate all pure strategies of each agent)
- Mixed strategy is set of mixed strategies in this image normal-form game
- Can also define behavioral strategies
 - Instead of randomizing over pure strategies, randomize independently at each node in a given information set



Example

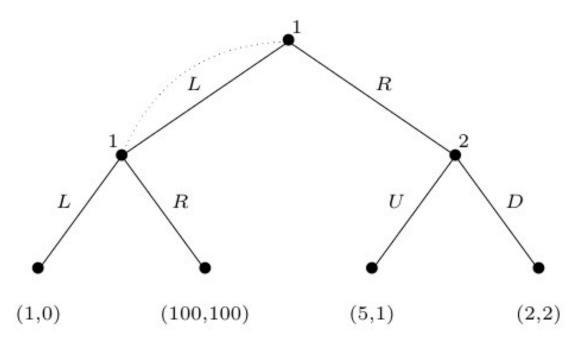


Figure 5.12: A game with imperfect recall



Perfect Recall

Every player remembers all of their previous choices

Definition 5.2.3 (Perfect recall) Player i has perfect recall in an imperfect-information game G if for any two nodes h, h' that are in the same information set for player i, for any path $h_0, a_0, h_1, a_1, h_2, \ldots, h_m, a_m, h$ from the root of the game to h (where the h_j are decision nodes and the a_j are actions) and for any path $h_0, a'_0, h'_1, a'_1, h'_2, \ldots, h'_{m'}, a'_{m'}, h'$ from the root to h' it must be the case that:

- 1. m = m';
- 2. for all $0 \le j \le m$, if $\rho(h_j) = i$ (i.e., h_j is a decision node of player i), then h_j and h'_j are in the same equivalence class for i; and
- 3. for all $0 \le j \le m$, if $\rho(h_j) = i$ (i.e., h_j is a decision node of player i), then $a_j = a'_j$.

G is a game of perfect recall if every player has perfect recall in it.



Theorem 5.2.4 (Kuhn, 1953) In a game of perfect recall, any mixed strategy of a given agent can be replaced by an equivalent behavioral strategy, and any behavioral strategy can be replaced by an equivalent mixed strategy. Here two strategies are equivalent in the sense that they induce the same probabilities on outcomes, for any fixed strategy profile (mixed or behavioral) of the remaining agents.



Imperfect-Information, Extensive-Form Games: Computing Equilibria with Sequence Form

Sequence-Form Representation

Definition 5.2.6 (Sequence) A sequence of actions of player $i \in N$, defined by a node $h \in H \cup Z$ of the game tree, is the ordered set of player i's actions that lie on the path from the root to h. Let \emptyset denote the sequence corresponding to the root node. The set of sequences of player i is denoted Σ_i , and $\Sigma = \Sigma_1 \times \cdots \times \Sigma_n$ is the set of all sequences.

Definition 5.2.7 (Payoff function) The payoff function $g_i : \Sigma \mapsto \mathbb{R}$ for agent i is given by $g(\sigma) = u(z)$ if a leaf node $z \in Z$ would be reached when each player played his sequence $\sigma_i \in \sigma$, and by $g(\sigma) = 0$ otherwise.



Sequence-Form Representation

Definition 5.2.5 (Sequence-form representation) Let G be an imperfect-information game of perfect recall. The sequence-form representation of G is a tuple (N, Σ, g, C) , where

- N is a set of agents;
- $\Sigma = (\Sigma_1, \dots, \Sigma_n)$, where Σ_i is the set of sequences available to agent i;
- $g = (g_1, \ldots, g_n)$, where $g_i : \Sigma \mapsto \mathbb{R}$ is the payoff function for agent i;
- $C = (C_1, ..., C_n)$, where C_i is a set of linear constraints on the realization probabilities of agent i.



Example

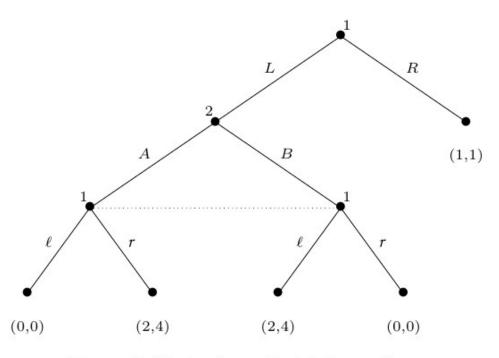


Figure 5.10: An imperfect-information game.

$$\Sigma_1 = \{\emptyset, L, R, L\ell, Lr\} \text{ and } \Sigma_2 = \{\emptyset, A, B\}.$$



Example

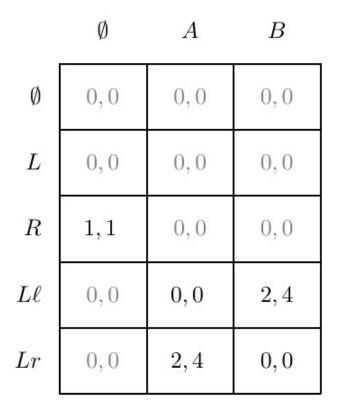


Figure 5.13: The sequence form of the game from Figure 5.10.

	A	B
$L\ell$	0,0	2,4
Lr	2,4	0,0
$R\ell$	1,1	1,1
Rr	1,1	1,1

Figure 5.14: The induced normal form of the game from Figure 5.10.



Sequence-Form Representation

- But how does player select a sequence?
 Depending on what other players select, not all sequences are valid
- behavioral strategy: probability $\beta_i(h, a_i)$ of taking action a_i at node h

Definition 5.2.8 (Realization plan of β_i) *The* realization plan of β_i for player $i \in N$ is a mapping $r_i : \Sigma_i \mapsto [0,1]$ defined as $r_i(\sigma_i) = \prod_{c \in \sigma_i} \beta_i(c)$. Each value $r_i(\sigma_i)$ is called a realization probability.



Sequence-Form Representation

Definition 5.2.9 (Realization plan) A realization plan for player $i \in N$ is a function $r_i : \Sigma_i \mapsto [0, 1]$ satisfying the following constraints.

$$r_i(\emptyset) = 1 \tag{5.1}$$

$$\sum_{\sigma_i' \in \text{Ext}_i(I)} r_i(\sigma_i') = r_i(\text{seq}_i(I)) \qquad \forall I \in I_i$$
 (5.2)

$$r_i(\sigma_i) \ge 0$$
 $\forall \sigma_i \in \Sigma_i$ (5.3)

$$\beta_i(h, a_i)$$
 is defined as $\frac{r_i(\text{seq}_i(I)a_i)}{r_i(\text{seq}_i(I))}$



Computing best response

maximize
$$\sum_{\sigma_1 \in \Sigma_1} \left(\sum_{\sigma_2 \in \Sigma_2} g_1(\sigma_1, \sigma_2) r_2(\sigma_2) \right) r_1(\sigma_1)$$
 subject to $r_1(\emptyset) = 1$ (5.4)

$$\sum_{\sigma_1' \in \operatorname{Ext}_1(I)} r_1(\sigma_1') = r_1(\operatorname{seq}_1(I)) \qquad \forall I \in I_1 \qquad (5.6)$$

$$r_1(\sigma_1) \ge 0$$
 $\forall \sigma_1 \in \Sigma_1$ (5.7)

Dual:

minimize
$$v_0$$
 (5.8) subject to $v_{\mathcal{I}_1(\sigma_1)} - \sum_{I' \in \mathcal{I}_1(\operatorname{Ext}_1(\sigma_1))} v_{I'} \ge \sum_{\sigma_2 \in \Sigma_2} g_1(\sigma_1, \sigma_2) r_2(\sigma_2) \quad \forall \sigma_1 \in \Sigma_1$ (5.9)



Computing equilibria of two-player, zero-sum

minimize
$$v_0$$
 (5.10) subject to $v_{\mathcal{I}_1(\sigma_1)} - \sum_{I' \in \mathcal{I}_1(\operatorname{Ext}_1(\sigma_1))} v_{I'} \ge \sum_{\sigma_2 \in \Sigma_2} g_1(\sigma_1, \sigma_2) r_2(\sigma_2) \quad \forall \sigma_1 \in \Sigma_1$ (5.11)
$$r_2(\emptyset) = 1 \qquad (5.12)$$

$$\sum_{\sigma'_2 \in \operatorname{Ext}_2(I)} r_2(\sigma'_2) = r_2(\operatorname{seq}_2(I)) \qquad \forall I \in I_2 \quad (5.13)$$

$$r_2(\sigma_2) \ge 0 \qquad \forall \sigma_2 \in \Sigma_2 \quad (5.14)$$



Imperfect-Information, Extensive-Form Games: Sequential Equilibria



On Equilibria

- Recall that Nash equilibrium was too weak of a concept for perfect information games
- Subgame-perfect equilibrium
- Q: Can we generalize this notion to imperfect information games?



Subgame-Perfect?

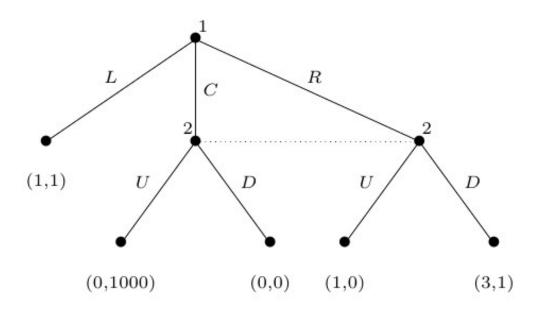


Figure 5.15: Player 2 knows where in the information set he is.

Nash equilibria are (L,U) and (R,\bar{D}) .



Sequential Equilibrium

- Fully mixed strategy gives positive probability to every node in the game tree
- Makes sense to talk about expected utility given that we are in a specific subtree (using Bayes' rule)
- What about if strategy isn't fully mixed?
- We say probability distribution is consistent with strategy strategy profile if it agrees with Bayes' rule for subtrees with nonzero probability



Sequential Equilibrium

 Expected utility at h given strategy profile s and probabiloity distribution:

$$u_i(s \mid h, \mu(h)).$$

Definition 5.2.10 (Sequential equilibrium) A strategy profile s is a sequential equilibrium of an extensive-form game G if there exist probability distributions $\mu(h)$ for each information set h in G, such that the following two conditions hold:

- 1. $(s,\mu) = \lim_{m\to\infty} (s^m,\mu^m)$ for some sequence $(s^1,\mu^1),(s^2,\mu^2),\ldots$, where s^m is fully mixed, and μ^m is consistent with s^m (in fact, since s^m is fully mixed, μ^m is uniquely determined by s^m); and
- 2. For any information set h belonging to agent i, and any alternative strategy s'_i of i, we have that

$$u_i(s \mid h, \mu(h)) \ge u_i((s', s_{-i}) \mid h, \mu(h)).$$



Sequential Equilibrium

Theorem 5.2.11 Every finite game of perfect recall has a sequential equilibrium.

Theorem 5.2.12 In extensive-form games of perfect information, the sets of subgame-perfect equilibria and sequential equilibria are always equivalent.

